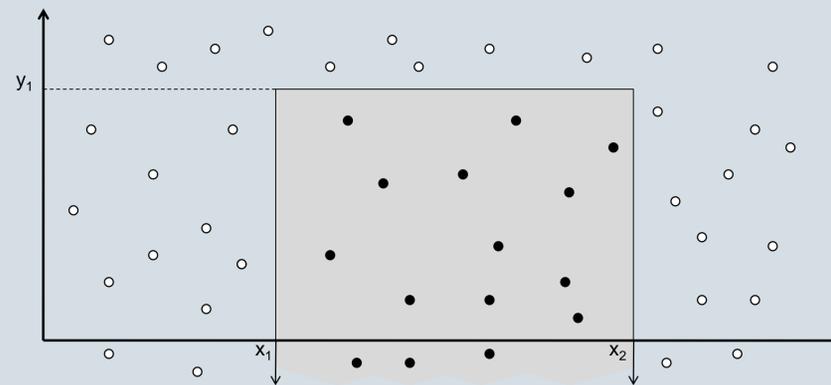


# Orthogonal Planar 3-sided Range Reporting

Store  $n$  points  $(x,y)$  in the 2-dimensional plane, such as to **report** all  $t$  points that lie within any query region of the form  $[x_1, x_2] \times (-\infty, y_1]$ , namely a **three-sided rectangle** with one side unbounded.

The dynamic setting allows for **insertions** and **deletions** of points (updates).

Efficiency (Complexity) is measured in terms of (**S**: used space, **Q**: query time, **U**: update time).



This is a basic problem in computational geometry and finds applications in spatial databases, computer graphics, geographic information systems, and more areas.

Internal Memory	Pointer Machine	Random Access Machine	Static Setting	
	<p>Data resides in <u>records</u> (nodes) that can be accessed via <u>pointers</u> (links).</p> <p>The <b>priority search tree</b> achieves <math>(n, \log n + t, \log n)</math>. [McCreight, SIAM J.Comp.'85]</p>	<p>Data is stored in an infinite <u>array</u> of cells, each containing a <u>word</u> of bits. A CPU can access any cell and perform arithmetic or bitwise <u>operations</u>.</p> <p>The <b>fusion tree</b> achieves <math>(n, \frac{\log n}{\log \log n} + t, \frac{\log n}{\log \log n})</math> or <math>(n, \sqrt{\log n} + t, \sqrt{\log n})</math> where Q and U are expected bounds [Willard, SODA'92]. [Mortensen, SODA'03] reduces U achieving <math>(n, \frac{\log n}{\log \log n} + t, \log^\omega n)</math>, <math>\omega &lt; 1</math>.</p>	<p><b>Probabilistic Distributions and Our Results</b></p> <p>Q and U can be significantly reduced if we assume that the coordinates are being drawn from an unknown, continuous <math>\mu</math>-random distribution.</p> <p>Two examples are the <u>Zipfian distribution</u>, which is commonly used in practice, and the <u>Smooth distribution</u>, which is a generalization of many known distributions.</p>	<p>In the pointer machine <math>(n, \log \log n + t, -)</math> is possible, when no updates are allowed [Mehlhorn, A. Tsakalidis et al., IPL'87].</p> <p>In the RAM, when the x-coordinates are integers in the range <math>[N]</math> (<u>rank space</u>), <math>(N + n, 1 + t, -)</math> is possible. When both x- and y-coordinates are integers one can achieve <math>(n, \log \log N + t, -)</math> [Brodal et al., FOCS'00].</p>
External Memory	I/O Model		Cache-oblivious Model	
	<p>The aforementioned models are insufficient to capture the complexity of algorithms running on modern computers. In fact, modern architectures consist of a <u>memory hierarchy</u>, where the bottleneck lies on the transfer of data between consecutive levels, rather than on computation itself.</p>		<p>The Input/Output Model (I/O model) studies two consecutive levels of the memory hierarchy. Data resides in an <u>external memory</u> that consists of blocks of size B. An <u>I/O operation</u> transfers a block to the <u>internal memory</u> of size M, where computation is performed for free. [Aggarwal, Vitter, C.ACM'88]</p> <p>The <b>external priority search tree</b> is the most efficient data structure for this model and attains <math>(\frac{n}{B}, \log_B n + \frac{t}{B}, \log_B n)</math> [Arge et al., PODS'99].</p>	<p>We attain <math>(n, \log n + t, \log \log n)</math> when both x- and y-coordinates are <math>\mu</math>-random, and <math>(n, \log \log n + t, \log \log n)</math> when furthermore x is zipfian. All reduced complexities are expected with high probability [K.Tsakalidis et al., ICDT'10]. The latter bounds hold also when x is smooth. U becomes expected amortized [K.Tsakalidis, Brodal et al., ISAAC'09].</p> <p>Accordingly, in the I/O model, we attain <math>(\frac{n}{B}, \log_B n + \frac{t}{B}, \log_B \log n)</math> when both x and y are <math>\mu</math>-random. When x is zipfian and y is smooth, then <math>(\frac{n}{B}, \log_B \log n + \frac{t}{B}, \log_B \log n)</math> can be attained. All reduced complexities are expected with high probability. [K.Tsakalidis et al., ICDT'10] <math>(\frac{n}{B}, \log \log_B n + \frac{t}{B}, \log_B \log n)</math> can be achieved by only assuming that x is smooth. Here, U is expected amortized. [K.Tsakalidis, Brodal et al., ISAAC'09]</p>