

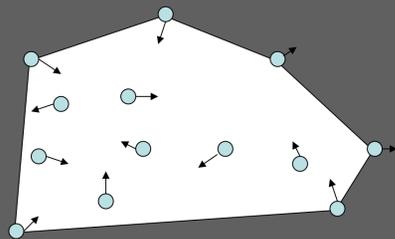
# Kinetic Data Structures

## Motivation

Motion is ubiquitous in the physical world and due to recent advances in sensing and tracking technology, motion data is becoming more and more available in a variety of areas: mobile communication, geographic information system, air-traffic control, and so on. It is not surprising, therefore, that it is necessary to store, analyze, and create or manipulate motion data. As a result, modeling moving objects has become an important area of study in many areas of computer science such as computation geometry, databases, graphics, wireless networks, ....

## Geometric study of moving objects

Simulate system of continuously moving objects and efficiently maintain discrete geometric attributes of objects such as the convex hull of moving points.



## Two main approaches

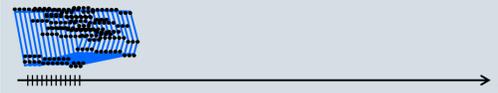
- Time sampling
- Kinetic data structures

## Time Sampling Approach

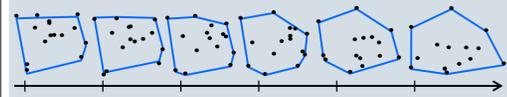
- Choose fixed time step.
- Update the positions of moving objects at each time step.
- Update the data structure with the new positions of objects.

### How to choose time step?

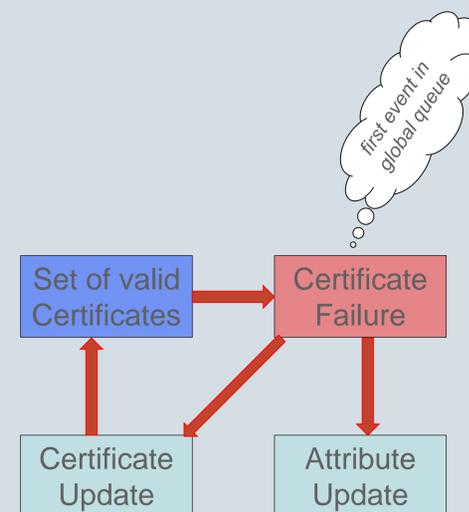
- Oversampling:



- Undersampling

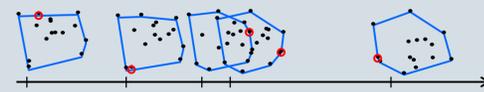


## KDS Framework



## Kinetic Data Structures

- Combinatorial changes occur in irregular patterns.



### KDS consists of two parts

- Combinatorial description of the attribute.
- A set of certificates—elementary test on the input objects—with the property that as long as the outcome of the certificates do not change, the attribute does not change.

## KDS Properties

- Compact:** if it uses little space in addition to the input.
- Responsive:** if data structure invariants can be restored quickly after the failure of a certificate.
- Local:** if it can be updated easily if flight plan for an object changes.
- Efficient:** if the worst-case number of events handled by the data structure is small compared to some worst case number of external events.

## Structures

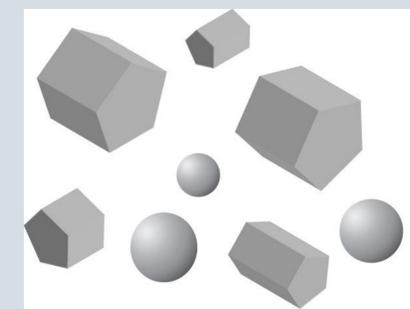
- Proof of correctness of attribute (**certificates**)
- Priority queue (**event queue**)

## Assumptions

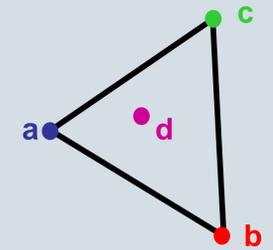
- A simple model for motion: each object follows a known **flight plan** with rational parameters.
- Certificates are algebraic; failure is next largest root.

## Collision Detection

Kinetic methods can be applied to collision detection problem which is a basic problem arising in all areas of geometric modeling involving objects in motion—**motion planning, computer-simulated environments, ...**



## Example



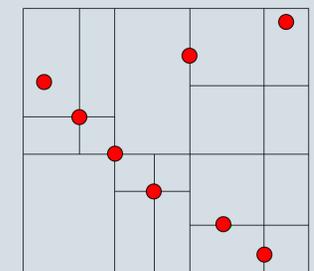
### Certificates

- a is to the left of bc
- d is to the left of bc
- b is to the right of ad
- c is to the left of ad

## Query Data Structures

Kinetic method can be used to maintain a QDS in order to quickly answer queries involving objects in motion:

- What are the points currently inside a given region?
- What is currently are nearest point to a given query point?



Rank-based kd-tree is efficient to answer above queries.